

Typed Assembly for the Zarf ISA

Machine-Checked, Typed, Polymorphic, Functional Assembly Code

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This Talk

- Unpublished
- Thoughts on extensions to our prior work
- Seeing if anyone else cares
- Request for:
 - Feedback
 - Experiences
 - Related work to consider
- Get us thinking about applying PL techniques to the architecture world

Outline

- This Talk
- The Zarf Architecture
 - Untyped Machine
 - Semantics
- Typed Assembly Background
 - Advantages
- Typed Zarf
 - Typed Machine
 - Binary Type-checking Algorithm
 - Some Guarantees Zarf Gets
- The Future, and Why
 - Finding Motivation

The Zarf Architecture for Recursive Functions (ASPLOS 2017)

- An ISA based on the lambda calculus
 - Lambda-lifted, lazy, ANF, WHNF
 - 3 instructions
 - let: stores a thunk
 - **case**: thunk evaluation to WHNF for matching
 - result: yields value to case
 - terminates every instruction branch and function
 - Functions
 - User-defined
 - Builtins (add, mult, xor, etc.)
 - I/O: getint and putint
 - Constructors
 - Named tuples
 - Special error constructor to indicate HW error

Untyped Machine

	High-Level Assembly	Machin	ne Assembly		Bin	nary	77		Binary	Encoding	
1	cons nil	cons 0	# nil, 0x101	1	2	X	X		Functio	n Header	
2	cons cons head tail	cons 2	# cons, 0x102	1	0	X	X	isCons	nArgs	reserve	d nLocals
3	<pre>func map f l =</pre>	func 2 3:	# map, 0x103	Θ	2	X	3	1	11	10	10
4	case l of {	case [arg 1]		1	Х	0	1				
5	nil =>	pat_con [0x10]	1] 1	4	1	X	101		Instruct	ion Word	
6	l	result [arg]	1]	2	Х	0	1	ор	n	src	index
7	cons h tl =>	pat_con [0x102	2] 9	4	9	X	102	3	10	3	16
8	let h' = f h in	let [arg 0] 1	1	Θ	1	0	Θ				
9		[field 0]		3		0			Argume	ent Word	
10	let tl' = map f tl in	let [table 0;	x103] 2 # local 1	Θ	2	4	103	src		index	
11		[arg 0]		Θ		0		3	~	29	
12		[field 1]		3		1					
13	let l' = cons h' tl' in	let [table 0	x102] 2 # local 2	Θ	2	7	102	Op	ocodes	So	urces
14		[local 0]		1		0		0	let	0	arg
15		[local 1]		1		1		1	case	1	local
16	ι,	result [loca	l 2]	1	Х	1	2	2	result	2	literal
17		pat_else 2		5	2	X	X	3	pat_lit	3	field
18		let [table 0:	x0] 0	Θ	0	4	Θ	4	pat_con	4	table
19		result [loca	l 0]	2	Х	1	0	5	pat_else		

Semantics

 $c \in Constructor = Name \times Value$ $clo \in Closure = (\lambda \vec{x}.e) \times Value$ $v \in Value = \mathbb{Z} \ \uplus \ Constructor \ \uplus \ Closure$ $\rho \in Env = Variable \rightarrow Value$

 $\frac{\downarrow e \Downarrow v}{\sqrt{c} \ell \text{ fun main } = e \Downarrow v} \xrightarrow{(\text{PROGRAM})} \frac{v = \rho(arg)}{\rho + \text{result } arg \Downarrow v} \xrightarrow{(\text{RESULT})} \frac{\vec{v}_1 = \rho(\vec{arg}) \quad v_2 = \text{applyCn}(cn, \vec{v}_1) \quad \rho[x \mapsto v_2] + e \Downarrow v_3}{\rho + \text{let } x = cn \ \vec{arg} \ \text{in } e \Downarrow v_3} (\text{LET-CON})$ $x \in Variable \quad n \in \mathbb{Z} \quad fn, cn \in Name \quad \oplus \in PrimOp$ $\underbrace{fn \notin \{\text{getint}, \text{putint}\} \quad \text{fun } fn \ \vec{x}_2 = e_2 \in \overrightarrow{decl} \quad \vec{v}_1 = \rho(\overrightarrow{arg}) \quad v_2 = \text{applyFn}((\lambda \vec{x}_2.e_2, []), \vec{v}_1, \rho) \quad \rho[x_1 \mapsto v_2] \vdash e_1 \Downarrow v_3}_{\text{(LET-FUN)}}$ $\rho \vdash \mathbf{let} x_1 = fn \overrightarrow{arg} \mathbf{in} e_1 \parallel v_3$ $p \in Program := \overrightarrow{decl}$ fun main = e $\frac{(r_1 + \rho(x_2))}{\rho + \text{let } x_1 = x_2} \frac{\vec{r_1} \cdot \vec{r_2} \cdot \rho}{\vec{r_1} \cdot \rho + \nu_4} \frac{\rho(x_1 + \nu_3) + e \Downarrow \nu_4}{\rho + \text{let } x_1 = x_2} \frac{(r_1 + \nu_3) + e \Downarrow \nu_4}{(r_1 + \nu_4)} (\text{LET-VAR}) = \frac{n_2 \text{ is input from port } n_1 \cdot \rho(x + n_2) + e \Downarrow \nu_4}{\rho + \text{let } x = \text{getint } n_1 \text{ in } e \Downarrow \nu} (\text{GETINT})$ $decl \in Declaration ::= cons | func$ $cons \in Constructor ::= con cn \vec{x}$ $\frac{\vec{v}_1 = \rho(\vec{arg}) \quad v_2 = \operatorname{applyPrim}(\oplus, \vec{v}_1) \quad \rho[x \mapsto v_2] \vdash e \Downarrow v_3}{\rho \vdash \operatorname{let} x = \oplus \ \vec{arg} \ \operatorname{in} e \Downarrow v_3} (\operatorname{LET-PRIM}) \quad \frac{n_2 = \rho(arg) \quad \rho[x \mapsto n_2] \vdash e \Downarrow v}{\rho \vdash \operatorname{let} x = \operatorname{putint} n_1 \ arg \ \operatorname{in} e \Downarrow v} (\operatorname{PUTINT})$ func \in Function ::= fun fn $\vec{x} = e$ $\frac{(cn, \vec{v_1}) = \rho(arg) \quad (cn \ \vec{x} \Rightarrow e_1) \in \overrightarrow{br} \quad \rho[\vec{x} \mapsto \vec{v_1}] \vdash e_1 \Downarrow v_2}{\rho \vdash case \ arg \ of \ \overrightarrow{br} \ else \ e_2 \Downarrow v_2} \quad (case-con) \qquad \frac{n = \rho(arg) \quad (n \Rightarrow e_1) \in \overrightarrow{br} \quad \rho \vdash e_1 \Downarrow v}{\rho \vdash case \ arg \ of \ \overrightarrow{br} \ else \ e_2 \Downarrow v} \quad (case-Litr)$ $e \in Expression ::= let | case | res$ *let* \in *Let* ::= *let* $x = id \overrightarrow{arg}$ *in* e $\frac{(cn, \overrightarrow{v_1}) = \rho(arg) \quad (cn \ \overrightarrow{x} \Rightarrow e_1) \notin \overrightarrow{br} \quad \rho + e_2 \Downarrow v_2}{\rho + case \ arg \ of \ \overrightarrow{br} \ else \ e_2 \Downarrow v_2} \quad (case-else1) \qquad \frac{n = \rho(arg) \quad (n \Rightarrow e_1) \notin \overrightarrow{br} \quad \rho + e_2 \Downarrow v_1}{\rho + case \ arg \ of \ \overrightarrow{br} \ else \ e_2 \parallel v_1} \quad (case-else2)$ $case \in Case ::= case arg of \overrightarrow{br} else e$ $res \in Result ::= result arg$ $pplyFn((\lambda \vec{x}_{1}.e, \vec{v}_{1}), \vec{v}_{2}, \rho) = \begin{cases} v & \text{if } |\vec{v}_{2}| = 0, |\vec{v}_{1}| = |\vec{x}_{1}|, \text{ and } \rho[\vec{x}_{1} \mapsto \vec{v}_{1}] \vdash e \Downarrow v \\ (\lambda \vec{x}_{1}.e, \vec{v}_{1}) & \text{if } |\vec{v}_{2}| = 0 \text{ and } |\vec{v}_{1}| < |\vec{x}_{1}| \\ applyFn((\lambda \vec{x}_{1}.e, \vec{v}_{1} :+ hd(\vec{v}_{2})), tl(\vec{v}_{2}), \rho) & \text{if } |\vec{v}_{2}| > 0 \text{ and } |\vec{v}_{1}| < |\vec{x}_{1}| \\ applyFn((\lambda \vec{x}_{2}.e', \vec{v}_{3}), \vec{v}_{2}, \rho) & \text{if } |\vec{v}_{2}| > 0, |\vec{x}_{1}| = |\vec{v}_{1}|, \text{ and } \rho[\vec{x}_{1} \mapsto \vec{v}_{1}] \vdash e \Downarrow (\lambda \vec{x}_{2}.e', \vec{v}_{3}) \end{cases}$ $br \in Branch ::= cn \vec{x} \Rightarrow e \mid n \Rightarrow e$ $id \in Identifier ::= x \mid fn \mid cn \mid \oplus$ $arg \in Argument ::= n \mid x$ $\operatorname{applyCn}(cn, \vec{v}) = \begin{cases} (cn, \vec{v}) & \text{if } (\operatorname{con} cn \vec{x}) \in \overrightarrow{decl} \text{ and } |\vec{v}| = |\vec{x}| \\ (\lambda \vec{x}. \operatorname{let} c = cn \vec{x} \text{ in result } c, \vec{v}) & \text{if } (\operatorname{con} cn \vec{x}) \in \overrightarrow{decl} \text{ and } |\vec{v}| < |\vec{x}| \end{cases} \quad \rho(arg) = \begin{cases} n & \text{if } arg = n \\ v & \text{if } arg = x \text{ and } (x \mapsto v) \in \rho \end{cases}$

Typed Assembly Background

TAL/TALx86 (Morrisett et al. 1999, Crary et al. 1999):

- High-level lang. compilation target
- Abstraction raised
 - word → integer, pointer, tuple, code labels
- Type constructors, parametric poly.
- Preconditions on code labels (register types)

STAL (Morrisett et al. 2002)

• Extend TAL with control stack

FunTAL (Patterson et al. 2017)

- Embed assembly in typed functional language and vice versa
- Reason about TAL components (mult. BBs) and high-level exp

Also:

- PCC (Necula and Lee, 1996)
 - Agent-supplied data/proof that it code complies with host's safety policies
- Typed intermediate languages

Typed Assembly Advantages

- High-level abstractions
 - enforced at machine level
 - can be ensured to be compiled/maintained correctly
- Help optimizations during entire compilation process
- Check untrusted code before running
 - Write in any language as long as it compiles down to TAL
- FunTAL: include speedy low-level operations and maintain guarantees

Typed Machine

	High-Level Assembly	I I	Aachine Assembly			Binar	y	
1	data List[a]	data 1 2	# List[a]	0x101	1	1	2	
2	= Nil	cons 0	# Nil	0x101	1		0	isData
3	Cons a List[a]	cons 2	# Cons	0x102	1		2	1
4		[tvar 0]			3		0	
5		[data 0x10	91]		1	0x	101	isCons
6		[tvar 0]			3		0	1
7	<pre>func map[a,b]:</pre>	func 2 2	# map	0x103	0	2	2	
8	$((a \rightarrow b),$	[func 1]			2		1	isCons
9		[tvar 0]			3		0	1
10		[tvar 1]			3		1	
11	List[a])	[data 0x10]	L]		1	Θx	101	type
12		[tvar 0]			3		Θ	2
13	\rightarrow List[b]	[data 0x10]	L]		1	0x	101	
14		[tvar 1]			3		1	op 3
15	<pre>func map f l =</pre>	def 0x103 3	# c	definition	0 (0x103	3	3
16	case l of {	case [arg 1	[]		1	X 0	1	
17	Nil =>	pat_con [0	0x101] 1		4	2 X	0x101	src
18	let n = Nil in	let [tab]	le 0x101] 0 # 1	local 0	Θ	9 4	0x101	3
19	n	result []	local 0]		2	X 1	Θ	
20	Cons h tl =>	pat_con [0			4	9 X	0x102	0
21	let h' = f h in			local 0	Θ	1 0	Θ	1
22		[field 0)]		3		Θ	
23	let tl' = map f tl in	let [tab]	le 0x103] 2 # 1	local 1	Θ	2 4	0x103	Op
24	[arg 0]		0 0			0		
25		[field 1			3		1	1
26	let l' = Cons h' tl' in	let [tab]	le 0x102] 2 # 1	local 2	Θ	2 4	0x102	2
27		[local @	9]		1		Θ	3
28		[local 1	[]		1		1	4
29	ι,	result []	local 2]		2	X 1	2	5

Binary Encoding Data Declaration						
isData						
1	15		16			
	Table Declaration (Cons)					
isCons	nFields					
1	31					
	Table Declaration (Func)					
isCons		dex	nLocals			
1	1 Type	6	15			
type	i	ndex/nAr	gs			
2		30				
-		on Word				
op 3	nArgs	src	index			
3	10	3	16			
	Argument Word					
src		index	908992090000000000000000000000000000000			
3	29					
	Types					
0	int	2	func			
0 1	int data	2 3	func tvar			
-						
1	data	3				
1	data	3	tvar urces arg			
1 Opc 0 1	data odes let case	3 So 0 1	tvar ^{urces} arg local			
1 Opc 0 1 2	data odes let case result	3 50 0 1 2	tvar urces arg local literal			
1 Opc 0 1 2 3	data odes let case result pat_lit	3 0 1 2 3	tvar arg local literal field			
1 Opc 0 1 2	data odes let case result	3 50 0 1 2	tvar urces arg local literal			

Binary Type Checking Algorithm

- 1. Load argument and return types with type variables
- 2. For each instruction:
 - a. If **let**:
 - i. Lookup table type
 - 1. Load its expected arguments/fields, with fresh, consistent type variable indices
 - ii. Lookup argument types in environment (must be variables or primitives)
 - iii. Check types:
 - 1. Match concrete type constructor
 - 2. Add constraints between type variables
 - b. If case:
 - i. Lookup scrutinee type in environment
 - ii. Lookup data type (if not primitive)
 - 1. Load constructors, assign type of fields to types in scrutinee
 - iii. Check for totality of matching
 - c. If **result:**
 - i. Unify constraints, replace non-original type variables as needed
 - ii. Compare result to return type

Some Guarantees Zarf Gets

- Filters our bad behaviors
 - Casing on an underapplied thunk/constructor
 - Passing incorrect arguments, using return value incorrectly
 - Elimination of *some* runtime error constructors (still array-out-of-bounds possibilities)
- Removes the need for a compiler you totally trust
- All foreign untrusted binaries can be checked
 - Untyped Zarf already prohibits arbitrary control flow and memory access...
- It's lambda-calculus (basically), so verifying it should be eas(ier)
- Type-checking done in **HW**; cannot be circumvented
 - no variable length memory structures
 - fixed bit width
 - bounded state machine

Finding Motivation

- Why do we need another typed assembly?
- Is there a meaningful decrease in proof complexity by using Zarf?
- Is hardware type-checking feasible for a non-trivial type system?
- Is our type system expressive enough?
- What kind of type system do you want?
- What kind of errors do you want to prevent?
- Ideas and future work:
 - Implement on hardware (currently in our simulator)
 - Proofs
 - Dependent types
 - Effects
 - Use Zarf as an IR

Questions (and maybe answers)